

Lecture 3

Review Lie algebra is a vector space L together with a bilinear map

$[\cdot, \cdot]: L \times L \rightarrow L$ such that:

$$(L1): [x, x] = 0, \quad (L2) \text{ (Jacobi id)} \quad [x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0 \quad \forall x, y, z \in L.$$

Rmk (L1) \Rightarrow (L1)': $[x, y] = -[y, x]$

Def A Lie subalgebra is a subspace K such that:

$$[K, K] := \{[x, y] \mid x, y \in K\} \subseteq K.$$

• many of our examples were subalgebras of $\mathfrak{gl}(n, F)$.

Def An ideal is a subspace K such that:

$$[K, L] := \{[k, x] \mid k \in K, x \in L\} \subseteq K$$

Rmk ideal \Rightarrow subalgebra

Key example

The center $Z(L) := \{z \in L \mid [x, z] = 0 \quad \forall x \in L\}$
is trivially an ideal.

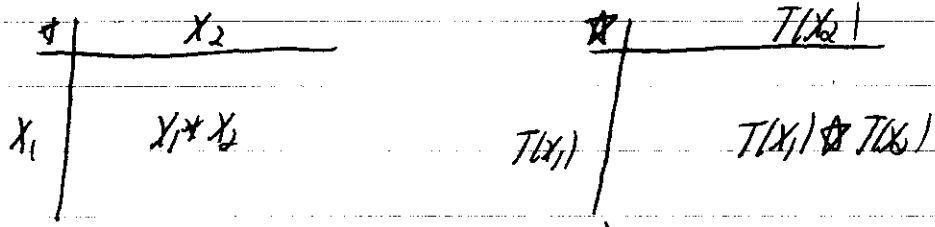
$$Z(L) = L \iff L \text{ is abelian.}$$

Rmk $[x, z] = 0 \quad \forall x \in L \iff \{[x_i, z] = 0 \mid x_i \text{ in a basis of } L\}$
so given structure constants, finding $Z(L)$ is just solving a system of linear equations

Ex $L = \mathfrak{sl}(F)$, $e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\begin{aligned} [h, e] &= 2e \\ [h, f] &= -2f \\ [e, f] &= h \end{aligned}$$

Homomorphisms General setup: $(X, *)$, (Y, \star) sets with binary ops $*$, \star , $T: X \rightarrow Y$



Want: $T(x_1 * x_2) = T(x_1) \star T(x_2)$

Ex Linear map: $T(x_1 + x_2) = T(x_1) + T(x_2)$, $T(\lambda x_1) = \lambda T(x_1)$
Group homom, Ring homom, etc.

Def Let L_1, L_2 be Lie algebras over F . A map $\psi: L_1 \rightarrow L_2$ is a Lie algebra homomorphism if it is linear and:

$$\psi([x, y]) = [\psi(x), \psi(y)] \quad \forall x, y \in L_1$$

If ψ is 1-1 and onto then ψ is an isomorphism and $L_1 \cong L_2$

Ex (Most important of all!)

L a Lie alg. Recall $\mathfrak{L}(L) =$ Lie alg of all linear maps $L \rightarrow L$,
 $[a, b] = ab - ba$.

The adjoint homomorphism

$ad: L \rightarrow \mathfrak{L}(L)$ is defined by

$$(ad x)(y) = [x, y] \quad \forall x, y \in L, \text{ i.e. } x \rightarrow [x, -]$$

• $[x, -]$ clearly linear

Need $ad([x, y]) = [ad x, ad y]$, so apply both sides to $z \in L$.

(3)

Need $[X, Y], Z] = \text{adx} \circ \text{ady}(Z) - (\text{ady} \circ \text{adx})(Z)$
 $= [X, [Y, Z]] - [Y, [X, Z]]$

use $[a, b] = -[b, a] + \text{J.I.}$ //

Lemma Let $\psi: L_1 \rightarrow L_2$ be a Lie alg. homo. Then $\text{Ker } \psi = \{x \mid \psi(x) = 0\}$ is an ideal.

Proof Let $x \in \text{Ker } \psi, y \in L_1$.

$$\psi([x, y]) = [\psi(x), \psi(y)] = [0, \psi(y)] = 0$$

so $[x, y] \in \text{Ker } \psi$ //

Ex $\text{Ker}(\text{ad}) = Z(L)$ by definition.

Rank ad is our first example of a representation, namely a Lie alg homo. $L \rightarrow \mathfrak{gl}(V)$ for some V .

Derivations

Let A be an F -algebra. A derivation of A is a linear map $D: A \rightarrow A$ such that

$$D(ab) = aD(b) + D(a)b \quad \forall a, b \in A.$$

Prop. Let $\text{Der } A$ be the set of all derivations of A . Then $\text{Der } A$ is a Lie subalgebra of $\mathfrak{gl}(A)$.

Proof.

1. Check $\text{Der } A$ is a subspace. (easy)

2. Let D_1, D_2 be derivations. Need: $[D_1, D_2]$ is also.

$$[D_1, D_2](ab) \stackrel{?}{=} a \cdot [D_1, D_2](b) + [D_1, D_2](a) \cdot b \quad ?$$

$$\begin{aligned} \text{LHS } (D_1 \circ D_2 - D_2 \circ D_1)(ab) &= D_1 \circ D_2(ab) - D_2 \circ D_1(ab) \\ &= D_1(a D_2(b) + D_2(a) b) - D_2(a D_1(b) + D_1(a) b) \\ &= a D_1 D_2(b) + D_1(a) D_2(b) + D_2(a) D_1(b) + D_1 D_2(a) b \\ &\quad \text{etc.} \end{aligned}$$

Two Key Examples

1. $A = C^\infty(\mathbb{R}) =$ only diff functions $\mathbb{R} \rightarrow \mathbb{R}$
 Define $(fg)(x) = f(x)g(x)$, A is an assoc \mathbb{R} -alg

Then $D(f) := f'$ is a derivation

2. $\text{ad}: L \rightarrow \mathfrak{gl}(L)$
 Image $\in \text{Der}(L) \subseteq \mathfrak{gl}(L)$

Problems

1.13, 1.15, 1.17

HW 1.9, 1.14, 1.18, 2.6, 2.8, 2.9, 2.11